



AZ-MC1 Multi-station-CNC-control

NC - Commissioning

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<inb0898.docec>



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1 Commissioning

Commissioning is part of the programming module and can thus be reached only by pressing the $\begin{bmatrix} Data \\ Pata \end{bmatrix}$ key on the operating panel. On first selection the entire menu can be protected by a password.

1.1 First commissioning

At the first commissioning of an unconfigured AZ-MC1, it is initially necessary to load the AZ-MC1 with the necessary configuration data and axis parameters, as well as a PLC program. This is done by the following operations:

	NC1 : ready ····
File	Commisioning Options Help
	NC configuration configuration op.panel
	Backup-path: :\amk\nc\nc_prog\backup\
	< OK >
	EA-programming MBT-programming
	Password File Password Commisioning
Back	up-path File- transfer ***

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- 1. The backup path must be set up -if not yet done- in the "Commissioning Configuration OP ' menu item (see above picture)
- 2. The configuration data of the NC must be generated with the NC configuration program and transferred from there into the backup path of the machine.
- 3. Generate a PLC program with the 'APROS' program and load it into the backup path of the machine or make use of a standard PLC program which is loaded into the path.
- 4. Load the generated data records and the programs on the MC1 in the 'Commissioning Load nc-setup' menu item.
- 5. Most of the data become effective only after renewed booting of AZ-MC1 and OP, i.e. switch both off and back on.
- 6. The data records can be edited in the 'Commissioning NC Configuration' menu item. These become valid by renewed booting of AZ-MC1 and OP.
- 7. Perform a complete backup of the data to back up all changes through the 'Commissioning Save nc-setup' menu item.

The commissioning pulldown menu offers the following selection:

	NC1 : ready ····	
File	Commissioning Options H	Help
	NC configuration configuration op.panel APROS diagnostics	
	Save nc setup Load nc setup	
	EA-programming MBT-programming	
	Password File Password Commissioning	
		-

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1.2 NC configuration

Several dialog pages belong to the NC configuration. You change between these with the softkeys. The entries do not become valid until the OK box in one of the dialog pages is confirmed with *Enter*. As long as this has not been done, the entries made up to then (i.e. the entries on all pages) can be rejected again with **A**.

You move between the entries inside a dialog page with the $\stackrel{\text{Enter}}{\checkmark}$ and $\stackrel{\text{Letter}}{\checkmark}$ keys forwards and by means of $\stackrel{\text{Letter}}{\bullet}$ backwards.

If several NC machines are connected to the control panel, firstly select those for which the following entries apply.

	NC1 : readu			
File	File Commissioning Ontions Heln			
	NC configuration			
	Name of machine:	NC1		
	NC-Туре:	(*) Common () Workpiece store () Handling		
	NC start:	[] without axis reset		
	ISO programs:	[] restore		
		< OK >		
L				
Gen	nera l Manua l	Homing M-function Axis Autostart *		

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General

General	
Machine name:	Name of the machine, max. 8 characters. The machine name serves for identifying the NC machine. It is required primarily in multimachine operation and for backup of the data records. Each machine receives a default name from the operating program which mirrors its position in the bus system. This default name should be changed by the operator corresponding to the task of the machine.
NC type:	Here you can define if the machine is not a general but a special machine (e.g. part accumulator). Special menu and dialog items extending general operation also exist in part for these machines.
NC start:	You can define with this option that the NC start command should be implemented in the NC machine without position setting, i.e. considerably faster.

ISO programs: This specifies that at the start of the interface, the ISO programs are transferred from the NC into the OP.

Manual

	NC1 : read	y			
File	Commision	ing Options H	elp		
	NC confi	guration			
	Axis:	[+] X-Axis [+] Y-Axis [+] Z-Axis [+] U-Axis	Type of handwheel:	 (*) No handwheel () Global handwheel () Local handwheels 	
		[+] V-Axis	Pulses/rev:	1000	
			Local handwheels:	[] X-Axis [] Y-Axis [] Z-Axis [] U-Axis [] V-Axis	
				< OK >	
Ge	meral	Manua I He	cycle	Ax1s Autostart	×

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Handwheel type:	no handwheel -> no handwheel is connected global handwheel -> one handwheel is used for all axes local handwheels -> each axis has its own handwheel
Sync-Z:	Factor for assessing the handwheel increments
local handwheels:	List of the connected local handwheels
Homing cycle Homing cycle:	Selection whether the common homing cycle should take place through a string or a DIN program.
DIN program:	The homing cycle program can be edited after pressing the key on the edit field
Reference string:	Configuration of the reference string for each existing axis: the larger the number, the later is the corresponding axis started. A zero means that the axis is not included in the string.
M function	

Activation of the required M function of the NC. With variable M functions, the type of synchronization and the couple bit to the PLC must be specified in addition.

M function:	Entry of the M function to be edited
M-Sync:	Activation and selection of the wanted synchronization.
Input:	Number of the coupling input to the PLC
Bit:	Number of bits inside the coupling input

Axis

File	NC1 : ready	-	
rne	commistering options help	,	
	NC configuration		
	Axis:	YCVBNMZU	
	hom.cucle offs. [mm]:	0.000	axis type:(+) Path
	resolution 1.D:	0	() Trafo-mach
	resolution_1.N:	0	() Trafo
	resolution_2.D:	0	() Route
	resolution_2.N:	0	() Spindle1
	accur.stop window [mm]:	10.000	() Spindle2
	pos. softw.limit [mm]:	0.000	() Synchron1
	neg. softw.limit [mm]:	0.000	() Synchron2
	feed limit [mm/min]:	0.00	() other
	max.feed [mm/min]:	0.00	
	accel.step1 [m/s²]:	0.00	
	accel.step2 [m/s²]:	0.00	
	ch.ov. feedr. [mm/min]:	0.00	
	max. feed ov.[%]:	0.0	
	leading axis:	0	< OK >
Cer	nenal Manual Homi	ing M_fun	ction Avis Autostant
der		le III-run	national nat

Axis

Name of the axis to which the following entries of this dialog part refer. The relevant axis can be selected with the cursor keys as long as the bar cursor is on the axis selection line. Editing the data of the

selected axis is made possible with ^{Enter} or 🚺 . The meaning of the axis data is described in the NC Configuration document. The following entries are offered for a linear axis:

Shifting the machine zero. Entry of the conversion factors between metric and incremental measuring system
27
"
Position window for in-position programming function (G60)
Positive software limit switch
Negative software limit switch
Feed limitation can be activated by PLC
Maximum feed speed
Definition of the acceleration ramps
"
"
Max. permissible feed override
Definition of the type of axis

Autostart

The autostart file consists of a ISO program which is executed in the NC automatically at the start of the operator interface. The ASCII editor is used to produce the file.

1.3 Operator Panel (OP) configuration

Several dialog pages belong to the OP configuration. You change between these with the softkeys. The entries are not valid until the OK box in one of the dialog pages is confirmed with $\[\]^{\text{Enter}}$. As long as this has not been done, the entries made by then (i.e. the entries on all pages) can be rejected again with $\[\]^{\text{Enter}}$.

You move with the and keys forwards and by means of backwards between the entries inside a dialog page.

	NC1 : ready	•••
File	Commissioning Opt	ions Help
	NC configuration configuration op.	pame 1
	Display:	<pre>[+] Actual position program [+] Actual position Machine [+] Actual pos. increment [+] General overview (Actual position program) [+] General overview (Actual position Machine) [+] NC program [+] NC block [+] Tool life [+] Graphics [+] Linking</pre>
	positions:	[+] to round
	Auto mode: NC-linking free:	[] NC program [+] Linking program < OK >
Di	splay Operation NC	SBUS Peripherals Free keys Linking »

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Displays

This dialog item specifies which data of the NCs are displayed in the NC operating module and in which manner. Several types of display between which it is possible to change at will in the on-line module can be selected.

Program actual position:	The actual positions (related to the programmed reference system) of all interpolatable axes are displayed in uppercase letters
Machine actual position:	The actual positions (related to the internal reference system of the machine) of all axes are displayed in uppercase letters
Ipos Increments:	The actual position increments of all axes are displayed in uppercase letters
Total overview (P):	The actual positions (related to the programmed reference system) and the residual distance of all interpolatable axes, current feed settings and the just executed NC block are displayed

Total overview (M):	The actual positions (related to the internal reference system of the machine) and the residual distance of all interpolatable axes, current feed settings and the just executed NC block are displayed
NC program:	The execution of the NC program can be followed in the source text

NC block:	All executed NC program blocks are displayed sequentially
Tool lives:	The current tool lives of all tools are displayed
Graphic:	The graphical display of the position of the first two NC axes is made
Linking:	Execution of the free linking program can be followed

With the 'round' option, it is specified whether positions should be displayed rounded in all types of display completely or to the last place but one.

NC operation

Jog feed:	Feed value without rapid traverse superimposition in mm/min (as F word) in the Jog or Step mode.
Jog fast feed:	Feed value with rapid traverse superimposition in mm/min (as F word) in the Jog or Step mode.
NC start:	If this option is set, a check is made before each NC start whether all axes are homed.
MDI:	An automatic line change takes place if this switch is set when executing DIN blocks in the MDI mode.

Sbus

The Sbus ports can be activated or deactivated with this. A physical address belongs to each port.

Serial interface 1 of the PC (OP)
Serial interface 2 of the PC (OP)
V422 interface of the adapter card
Fibre optic cable on the adapter card
Luminance of the fibre optic transmitter
Time (in s) which is waited in Sbus requirements

! Caution: The set values are used only at the next start of the OP!

Periphery

This dialog item consists of a list of all operating elements that can be activated and their current setting state:

le	NC1 : ready	- Om	tion	 z Helm						
5	NC configuration	tion	. nam							
		Tor	Msk	Pat		Tor	Msk	Pat	Max	Tab
	P_ACHSE:	-	00		P_NEG3:	-	00	00		
	P_HANDRAD1:	-	00	00	P_MASCHINE:	-	00			
	P_HANDRADZ:	-	00	00	P_NU_START:	-	00	00		
	P_HANDRAD3:	-	00	00	P_NC_STUP:	-	00	00		
	P_SILPSI:	_	00	00	P_FEEDH_E:	_	00	00		
	F_31LF3Z	_	00	00	T_TEEDU_H:	_	00	00	0	0
	P STEPS4	- 2	00	00	P SP OUFRR		00	00	0	0
	P J0G		00	00	P SP START	_	00	00	0	0
	P FAST:	_	00	00	P SP2 OUERR:	_	00	00	Û	Ð
	P POS:	_	00	00	P SP2 START:	_	00	00	0	9
	P NEG:	_	00	00	P BA HAND:	_	00	00		
	P POS1:	_	00	00	P BA AUTO:	_	00	00		
	P NEG1:	_	00	00						
	P_POS2:	-	00	00	axis name:					
	P_NEG2:	-	00	00						
	P POS3:	_	00	00		< (JK >			

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Apart from the designator, an entry consists of the following elements:

Gate:	Number of the input gate (0)
Msk (mask):	Masks the value read in by the input gate and thus also specifies right offsets
Pat (reservation):	Comparison value for determining the target state (for single switches) or threshold value for changes (for value switches)
Max:	Only for value switches: the maximum reservation of the maximum value assigned to the masked bits (only if no assignment table is active for the entry)
Tab:	Only for value switches: activation of an assignment table (by entering the value 1 or 2)

The assignment table serves for the completely free assignment of wanted values to input reservations. The table itself must be generated in the RED file in the form

P_TABELLE1 = 0,10,15,17,18,19,...

whereby a maximum of 32 values can be entered, i.e. the table can be applied to maximum 5 input bits. In the example, the value 0 is assigned to the input reservation 0, the value 10 to the input reservation 1, the value 15 to the input reservation 2 etc.

Additional explanations for the periphery can be found in the Diagnosis - Periphery' item chapt. 3.3.

A further input item serves for identifying the reservation of the axis selector switch:

Axis designation Designations (letters) of the axes on the axis selector switch

NC operating functions can be blocked with the aid of the peripheral functions P_BA_HAND and P_BA_AUTO (see Commissioning - OP Configuration - Periphery') item. If none of the two peripheral functions is activated (or defined), the blocks do not exist and all operating functions listed below are possible. This corresponds to the setting mode.

Operating function	Setting mode	Manual mode	Automatic mode
Set override	\checkmark	\checkmark	-
Set spindle override	\checkmark	\checkmark	-
MBF simulation	\checkmark	\checkmark	-
Machine operating panel	\checkmark	\checkmark	-
Edit in automatic/linking	\checkmark	\checkmark	-
Single operation in linking	\checkmark	\checkmark	-

Free keys

Reservation of the user keys <UK1>...<UK8> with freely selectable letters. These can be used both in the ASCII editor and also for axis selection in manual mode and for the homing cycle.

Linking

Linking choice of the type of linking in the NC operating module between programmed and parameterized linking. The further settings of the masked linkings are explained in a separate documentation.

Backup path

Complete path for the storage of settings (data record) and programs

File transfer

Interface:	Selection of the interface for the serial file transfer
Rate:	Transmission rate
Parity:	Parity check on file transfer
Bits:	Number of data bits
Stop:	Number of stop bits
BOT:	Definition of a beginning of transfer character; if none is defined, transmission and reception is without begin character
EOT	Definition of a end of transfer character; if none is defined, transmission and reception is without end character
BOK	Definition of a string marking the begin of head-data; if there is no defined, sending and receiving is done without this element.
EOK	Definition of a string marking the end of the head-data; if there is no defined, sending and receiving is done without this element.
BOD	Definition of a string marking the begin of each data-set; if there is no defined, sending and receiving is done without this element.
EOD	Definition of a string marking the end of all data-set; if there is no defined, sending and receiving is done without this element.

1.4 APROS

If this menu item is selected, the programmed logic controller (PLC) can be commissioned with the aid of the "APROS" program. If the program is not present on the OP, the menu item cannot be selected.

1.5 Saving and loading nc-configuration-data

There is always access to a backup medium from the NC operator interface. It is specified in the 'Commissioning - OP Configuration - Save nc-setup' menu item where this is located. It can be on a floppy disk drive (entry e.g. *b*:\) or the hard disk (e.g. *c*:*nc_prog\backup*). Backing up and loading data must be controlled by the operator using the following menu items:

1.5.1 Saving of nc-configuration data (Backup)

Using the 'Commissioning - Save nc setup' menu item, all files in the NC file management which are needed for the configuration

- of the NC (ncXX.cfg, geoXXN.cfg, sdaXXN.mds, axXXN.mds),
- of the associated PLC (p01.sps) as well as
- of the operator interface (pncN.red, modulN.dsc, autoN.)

are backed up on the backup medium in a directory with the name of the NC machine and the extension 'nc'.

They are reloaded using the 'Commissioning - Load nc setup' menu item.

1.5.2 Saving of part projects

Part projects are loaded to the backup medium in the 'Data input - Part project management - Backup part' menu item completely in a directory with the name of the project (without extension).

They are reloaded using the 'Data input - Part project management - Load part' menu item.

1.5.3 Saving of ISO programs

All DIN programs (those produced outside part projects) can be backed up jointly in the root directory of the backup medium in the 'Data input - ISO program management - Complete backup' menu item.

They are reloaded individually using the 'Data input - ISO program management - Load file' menu item.

1.5.4 Load nc setup

NC1 : ready	
Machine	data record
00H:NC1 00H:NC2 00H:NC3	021.NC 022.NC 023.NC 1AX_ZX.NC 1AX_K1.NC 1AX_K2.NC 2AX_XY.NC CONTUR95.NC DREHM.NC DREHM1.NC NC1.NC

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2 screen halves are offered, overwritten on the left with "Machine" (data destination) and on the right with "Data record" (data source). With an unconfigured NC, a standard designation of the NC[1-4] type appears under "Machine", which means as much as NC on the SBUS transmitter 1, physical subscriber number 4. The directory under which the data records are located in the backup path appears on the right. The directory name corresponds to the selected machine name with the extension *.NC, e.g. "021.NC". The cursor stands initially on the machine designation (NC[1-4]) and jumps by pressing to the right side for selection of the corresponding data record. Renewed pressing to the NC of the machine.

This is the reverse process of "Save nc-setup".

In the above picture, several machines are connected to one operating panel, so that a machine selection also takes place.

It is then necessary to switch both the operating panel and the machine (AZ-MC1) (power OFF) and to boot anew in order to work with the now valid data or to modify them.

1.6 I/O programming

The linkages of the I/O control are programmed in this menu item. The goal of the linkages consists in the programmable and thus variable "wiring" of all inputs and outputs of the NC interface among one another as well as to other processes (machine operating panel, linking).

The I/O program becomes active automatically after the start of the operator interface as well as also after editing and works constantly unnoticed in the background.

The ASCII editor serves for producing the I/O links. The links are described with the aid of a simple line-oriented language. Each line consists of an allocation of a source (Q) to a destination (Z) in the general type

Z = Q.

If no bits are specified, each element consists of one byte. Bits can be separated individually: **Z.bit = Q.bit**

or as group:

Z.bit..bit = Q.bit..bit

Thus, for instance, E0.2 means bit 2 of input 0. The expression E0.4..7 on the other hand separates the bits 4 to 7 from input 0.

Each source can be negated bit-wise in the allocation:

Z = !Q.

Comments are introduced by a semicolon and always extend up to the line end.

A maximum of 250 characters can be entered per line. The line can be lengthened by the backslash character (\) at the line end.

The following table provides an overview of the command set:

	Ζ	Q	Contents	Param. 1	Param. 2
Е		u	Peripheral inputs of the OP	Gate (011)	
Α	u		Peripheral outputs of the OP	Gate (03)	
G	u	u	Global status	ph. address (132) or machine	Byte (16)
Μ	u	u	Flag	Number (0255)	
\$	u	u u	Fixed addresses LINKING - IO of the linking MACHINE - Machine selection		

E Inputs

The binary (gate 0 to 3) and analog (gate 4 to 11) inputs of the OP are read by this.

Example: E0

A Outputs

The binary outputs of the OP are set.

Example: A1

G Global status		
As source:	A byte of the global Here the following v - The name of a ma - The physical addre - No subscriber is a	status of a Sbus subscriber becomes accessible. ariants are possible: chine is stated ess of a subscriber is stated (132) ddressed: the global status of the OP is read
As target:	A byte of the global another Sbus subsc with, but is not repo	status of the OP is set; the addressing of riber is ignored and can therefore be dispensed rted as error.
Note further that the by	ytes in the global stat	us are generally counted from 1 to 6.
Example:	G["Layout"]4 G4	as source as target

M Flag

The flag cells are read or set. All flag cells can be used bidirectionally and have a special meaning in the logical combination with other operating functions, like the machine control panel or the programmable linkage.

Example: M100

§ MACHINE fixed address

The selected machine number (value starting from 0) is accessible as source with this element.

Example: \$MACHINE

§ LINKING fixed address

The coupling bytes of the linking (one each as source and target) are accessible with this element.

The bits are defined specifically for both types of linking.

Example: \$LINKING

An example can look like the following: ;Transfer of the selected machine number to the PLC through global status G1.0..4 = \$MACHINE

;Transfer of free input ports to the PLC through global status G5 = E2 G6 = E3

;Bridging the clocking with linking without connected PLC \$LINKING = \$LINKING

1.7 Software Machine Panel (SMP) programming

An extensive software machine operating panel can be produced with SMP programming. It functions only in connection with the I/O control and uses its flags as general memory and for coupling with the actual I/O functions.

The operating panel does not become active until the corresponding function in the NC operating module is selected with and it is inactive if the function is exited again.

Three main types of element exist in the SMP:

- Dialog and display elements
- Elements for data coupling to the PLC
- NC control elements

The ASCII editor serves for producing the SMP elements. The elements are described with the aid of a simple line-oriented language. Each line consists of an allocation of an element to a flag (M) with the general syntax:

M Number { Typespec } allocation element

Apart from the separation of bits analogously to IO programming:

.bit	separates the bit
.bitbit	separates the bits fromto

extended data types can also be used as type specification:

-W	Word type (2 bytes), unsigned
-SW	Word type (2 bytes), signed
-L	Long type (4 bytes), unsigned
-SL	Long type (4 bytes), signed

If no type is specified, each element consists of one byte. The allocation defines whether the flag should be read and/or written:

=>	only read
<=	only write
=	read and write

whereby certain elements can be used only in one direction.

The following table shows an overview of the elements that can be used:

	S	L	Contents	Param. 2	Par. 3	
BS	u		Operating switch	Position	Text	
BT	u		Operating button	Position	Text	
BW	u		Operating menu	Position	Text list	
BA		u	Operating panel output (texts)	Position	Text list	
FT	u	u	Function button	Level (12)	Number (112)	Text
DIAL	u	u	Dialog or display	Position	Text	Places
BP	u	u	PDU memory field	Machine	Bytes (07)	
DB	u	u	Data block memory field	Machine	DB number (063)	Bytes (0125)
PSTART		u	Program start	Machine	Program number	

Position	- identifies the screen position (column, line), with max. 76 columns and
	18 lines,
Machine	- name of the NC machine
Text	 max. 20 or 11 characters, framed in quotation marks
Text list	- texts separated by commas
Places	- number of places / places after the decimal point

The texts in the operating elements and outputs can contain red letters apart from black letters. These must be enclosed in curved brackets. Nevertheless, these brackets are included in the number of characters.

Example: BA(10,1)" ","{Red}"

Comments are introduced by a semicolon and always extend up to the line end.

A maximum of 250 characters can be entered per line. The line is lengthened by the backslash character (\) at the line end.

BS Operating switch

The switch is displayed on the image at the defined position with the selected labelling. If the switch is actuated, its status changes (pressed / released). The pressed status is identified by the value 1, the released status by the value 0.

Example: M5 <= BS(1,1)"Switch"

BT Operating button

The operating button corresponds to an operating switch with the difference that it does not engage and therefore springs back into the quiescent state after a certain time.

|--|

BW Operating menu

The menu elements are displayed on the image starting from the defined position under one another with the selected labelling. The associated value is activated by activating an element. The first text has the value 0, the second the value 1 etc.

A blank place in the menu is generated by two commas within the text list without text in between.

Example:M0 <= BW(10,1)"One","Two","Three","Four","Five","Six","Seven","Eight"

BA Operating panel output

In each case one of the texts is displayed on the image starting from the defined position, if the assigned value corresponds to the value in the flag. The first text has the value 0, the second the value 1 etc.

Example: M0 => BA(1,15) "State 0","State 1","State 2","State 3"

FT Function buttons

The function buttons also do not engage like the operating buttons. They are shown in the grid of the softkeys and are assigned permanently to the 6 softkeys (FT number 1 to 6) and the 6 central free keys <Uk2> to >UK7> (FT number 7 to 12) located directly below. Several levels (currently 2) can be occupied and leafed through by means of the <ROLL> key. The pressed state is identified on writing by the value 1, the released state by the value 0.

Example: M3 <= FT[0]1,"Key"

When reading the value not equal to 0 is used to show the key marked. Thus it is possible to reflect pressing the key directly:

Example: M3 = FT[0]1,"Key"

or to use the marking as signal independent of the pressed state:

Example:	M3.0 <= FT[0]1,"Key"	
	M3.1 => FT[0]1	(a text may not be stated here!)

One sees with the last example that the two allocation directions can also be used separately for each FT function, in contrast to all other dialog or display elements.

DIAL Dialog / Display

This is a universal element for the display and/or input of a value, whereby this can be named towards the outside by a fixed text. The display of the value is specified by the number of places and, if required, by the number of places after the decimal point.

Example:	M7 = DIAL(30,1)"Value:"5	->	Value:	0	
	M7 = DIAL(30,1)"Value:"5,2	->	Value:	0.00	
	M7 = DIAL(30, 1)5	->	0		
	M7 = DIAL(30,1)5,2	->	0.00		

The type of allocation specifies whether the value should only be displayed (allocation: read only), the value should be corrected (allocation: read and write) or always newly overwritten (allocation: write only).

Example:	M7 => DIAL(30,1)"Value:"5	->	only display
	M7 = DIAL(30,1)"Value:"5	->	correction dialog
	M7 <= DIAL(30,1)"Value:"5	->	overwriting dialog

It is also possible with this element to display a fixed text (i.e. without display of a value). This is done by leaving out the place data. The assignment to a flag is then indeed redundant, but must be made for syntactic reasons:

Example: M7 = DIAL(40,1)"Solo"

BP PDU memory field

A PDU memory field becomes accessible to the PLC with this logical combination. It should be noted that currently only one PDU memory exists and therefore data can be exchanged only with one machine.

Example: M17 => BP["Layout1"]5 M18 <= BP["Layout1"]5 M19 = BP["Layout1"]0

DB Data block memory field

Areas of data blocks of the PLC are read and/or written byte by byte with this element.

Example:	M17 => DB["Layout1",1]5
	M18 <= DB["Layout1",1]5
	M19 = DB["Layout1",1]0

All DB elements which are only written are initialized on selection of the SMP function, i.e. the momentary reservation is read out from the PLC. Thus allocations for constant reading and writing are not necessary in the normal case.

PSTART Program start

This produces a (repeated) start of a DIN program in the stated machine. It must be possible to activate the program on the machine for this purpose (set project with automatic operation menu item). The start command is always triggered if the value is not equal to 0 and the machine is at rest.

Example: M100 => PSTART["Layout1",4000] -> Program 4000 is started

A small example can look like the following:

;Menu (actuators) and software buttons on the PLC through global status M2.0..6 <= BW(30,1) "One","Two","Three","Four","Five","Six","Seven","Eight","Nine" M2.7 <= BT(30,13) "Basic"

;Reservation display status from global status of machine "021" M5 => BA(30,15) "State 0","State 1","State 2","State 3"

;Starting the program on key pressure M1.0 = FT[0]1"Start machine" M1.0 => PSTART["Layout2",3000]

;Input of a value and transfer to PLC M10-L => DB["Layout2",1]20 M10-L = DIAL(1,1)"Number:"8

;Write long value ;Have long value entered

1.8 Password File

The file password serves for blocking the NC programming (off-line module) against unauthorized access. The term entered here is queried at the first transition NC operation =>NC programming. If the password was entered once correctly, the query is deactivated and becomes active again only by a restart of the operating program or by selection of this menu item (concluded with $\frac{\text{Enter}}{\text{D}}$).

1.9 Password Commissioning

The commissioning password serves for blocking the entire commissioning menu item against unauthorized access. The term entered here is queried at the first selection of this main menu item. If the password has been correctly entered once, the query is deactivated and becomes active again only by restart of the operating program.

2 Diagnosis

2.1 Diagnosis - SBUS

The SBUS is a local bus which is used to connect the NC operator interface with the NC machines and other AMKASYN components. Since this menu item is intended only for operators with special knowledge of the structure of the SBUS protocols, it is not explained further here.

2.2 Diagnosis - View trace

Certain events, such as error messages, are stored in the trace file. This file can be viewed by selecting this menu item. The ASCII editor is used in the read only mode for this purpose.

When evaluating the file note that this is filled according to the ring buffer principle, i.e. the last line of the file is not necessarily also the last written one.

2.3 Diagnosis - Periphery

This menu item serves for checking the directly connected operating elements.

NC1 : ready		
	peripherals	
0-300: 255 11111111	P_ACHSE	P_MASCHINE
1-301: 255 11111111	P_HANDRAD1	P_NC_START
2-302: 255 11111111	P HANDRAD2	P NC STOP
3-303: 255 11111111	P_HANDRAD3	P_FEEDH_E
4-310: 255 11111111	P STEPS1	P FEEDH A
5-311: 255 11111111	P STEPS2	P VB OVERR
6-312: 255 11111111	P STEPS3	P SP OVERR
7-313: 255 11111111	P STEPS4	PSPSTART
8-314: 255 11111111	PJOG	P SP2 OVERR
9-315: 255 11111111	PFAST	P SP2 START
A-316: 255 11111111	PPOS	P BA HAND
B-317: 255 11111111	P NEG	P BA AUTO
	P POS1	
	P NEG1	
0-300: 000 00000000	P POS2	
1-301: 000 00000000	P NEG2	
2-302: 000 00000000	P POS3	
3-303: 000 00000000	P NEG3	
Out0 Out1	Out2 Out3	

pic_l_6

All usable peripheral input and output gates are displayed in decimal and binary form with number, address and currently present value in the left part of the window.

The output gates can be set individually after pressing the keys <SOK1> to <SOK4>. Nevertheless, it can happen that this entered pattern is immediately written over again by the internal I/O control.

All activatable operating elements and their current setting state are displayed in the right part in the following form:

P_NAME [gate&mask:state]

The example: P_ACHSE [1&38:07]

means that the axis selector switch at the input gate 1 is connected. The bit pattern 38 (hex) is the mask for setting free the switch inputs (i.e. bits 3...5 of the gate). The switch is in the position 07 (i.e. axis 8 is set).

If no settings are displayed behind a name, the operating function is inactive. It is then implemented by OP key functions in many cases.

The following functions are currently implemented:

Name	Function	Example
P_ACHSE	Axis selection in manual mode	0,0x38
P_HANDRAD1	Mode selection for manual mode, handwheel with factor 1	1,0x07,0
P_HANDRAD2	Mode selection for manual mode, handwheel with factor 10	1,0x07,1
P_HANDRAD3	Mode selection for manual mode, handwheel with factor 100	1,0x07,2
P_STEPS1	Mode selection for manual mode, steps 0.01	1,0x07,3
P_STEPS2	Mode selection for manual mode, steps 0.10	1,0x07,4
P_STEPS3	Mode selection for manual mode, steps 1.00	1,0x07,5
P_STEPS4	Mode selection for manual mode, steps 10.0	1,0x07,6
P_JOG	Mode selection for manual mode, Jog movement	1,0x07,7
P_FAST	Switch-over key for rapid traverse in manual mode	0,0x04,1
P_POS	Pos. direction key for manual mode (variable axis)	0,0x01,1
P_NEG	Neg. direction key for manual mode (variable axis)	0,0x02,1
P_POS1	Pos. direction key for manual mode axis 1	
P_NEG1	Neg. direction key for manual mode axis 1	
P_POS2	Pos. direction key for manual mode axis 2	
P_NEG2	Neg. direction key for manual mode axis 2	
P_POS3	Pos. direction key for manual mode axis 3	
P_NEG3	Neg. direction key for manual mode axis 3	
P_MASCHINE	Selection of the selected station (machine)	2,0xf8
P_NC_START	NC start function for several NC operating functions	3,0x40,1
P_NC_STOP	NC stop function for several NC operating functions	3,0x80,1
P_FEEDH_E	Activate feedhold	
P_FEEDH_A	Deactivate feedhold	
P_VB_OVERR	Machine override setting	4,0xff
P_SP_OVERR	Spindle override setting	5,0xff
P_SP_START	I/O switching the spindle	
P_SP2_OVERR	Override setting for spindle 2	
P_SP2_START	I/O switching the spindle 2	
P_BA_HAND	Activating / deactivating the manual mode	
P_BA_AUTO	Activating / deactivating the automatic mode	

The functions P_POS... and P_NEG... serve for moving the axes in manual mode and thus also implicitly for stopping in Jog mode.

2.4 Diagnosis - Reservation of IO flags

The reservation of all IO flags can be viewed dynamically in this menu item.

	NC1	: re	ady														
								EA-I	Merke	er							
000:	000	000	000	000	000	000	000	000	000	000	000	000	000	000	000	000	
016:	000	000	000	000	000	000	000	000	000	000	000	000	000	000	000	000	
032:	000	000	000	000	000	000	000	000	000	000	000	000	000	000	000	000	
048:	000	000	000	000	000	000	000	000	000	000	000	000	000	000	000	000	
064:	000	000	000	000	000	000	000	000	000	000	000	000	000	000	000	000	
080:	000	000	000	000	000	000	000	000	000	000	000	000	000	000	000	000	
096:	000	000	000	000	000	000	000	000	000	000	000	000	000	000	000	000	
112:	000	000	000	000	000	000	000	000	000	000	000	000	000	000	000	000	
128:	000	000	000	000	000	000	000	000	000	000	000	000	000	000	000	000	
144:	000	000	000	000	000	000	000	000	000	000	000	000	000	000	000	000	
160:	000	000	000	000	000	000	000	000	000	000	000	000	000	000	000	000	
176:	000	000	000	000	000	000	000	000	000	000	000	000	000	000	000	000	
192:	000	000	000	000	000	000	000	000	000	000	000	000	000	000	000	000	
208:	000	000	000	000	000	000	000	000	000	000	000	000	000	000	000	000	
224:	000	000	000	000	000	000	000	000	000	000	000	000	000	000	000	000	
240:	000	000	000	000	000	000	000	000	000	000	000	000	000	000	000	000	
Mult	ipoiı	nt I	: 00	0 0:	000												
			_						-			_					
]]	Dez			Hex													
					_												
nic I	7																
r''_'_'																	

2.5 Diagnosis - Operating panel logout

The operating panel is immediately logged out in the NC on selection of this menu item. Thus another subscriber (e.g. PLC operating panel) is enabled to send movement commands to the NC.

2.6 Diagnosis - NC logout

The NC is immediately logged out from the drive commanding interface for the AZ-R01 on selection of this menu item. Thus it is possible to operate drives from the AZ operating panel (e.g. inching mode).

3 File and file management

3.1 Operator Panel

Start directory:

pnc.exe	Program for NC interface
pncstart.bat	Batch for starting the 'pnc.exe' and programs called by it
pncex.bat	This file is generated by 'pnc.exe' and therefore does not always have to be present
pnc.red	Settings for the OP (description see Appendix 5)

Overlays directory:

pnc_ger.hlp	Files for the on-line help (German and English)
pnc_eng.nip	
pnc_ger.lng	Files with texts for operation (German and English)
pnc_eng.lng	
pnc.ses	Settings for the OP (options)
pnctrace.txt	Trace file for error events
tskoment.hlp	Help texts for part memory
sp_abb.wsp	Status image of the part memory
sp_bak.wsp	
~?.tmp	Temporary data
~red?.tmp	

Amkglobl directory:

helvb.fon	Font file for title picture
amklogo.pcx	Image file with AMK logo
azr.err	Abbreviations of the error messages of the AZ computer
mc.err	Abbreviations of the error messages of the NC
ps.err	Abbreviations of the error messages of the PLC
psu.err	Abbreviations of the user error messages of the PLC
pnc.err	Abbreviations of the error messages of the NC operation
azr_ger.erh	Description texts for the error messages of the AZ computer (German)
mc_ger.erh	Description texts for the error messages of the NC (German)
ps_ger.erh	Description texts for the error messages of the PLC (German)
psu_ger.erh	Description texts for the error messages of the user PLC (German)
pnc_ger.erh	Description texts for the error messages of the NC operation (German)

User directory:

All programs and part projects produced by the programmer and intended for execution are stored in this directory. A separate subdirectory is created for each part project. The files which are produced without part project are filed in the basic directory of 'User'.

mdi.	MDI inputs		
pnc.ea	IO logical combinations (IO program)		
pnc.SMP	SMP elements		
*	DIN programs (consist of numerical name without extension)		
*.pnc	Project control files		
*.npv	Zero shift files		
*.wkz	Tool files		
*.wwz			
*.ZWZ			
*.kor	Offset data files		
*.vkt	Linking program files		
*.vkv			

3.2 NC file management

nc XX .cfg	Configuration data for the NC			
geo XXN .cfg	_ " _			
sda XXN .mds	_ " _			
ax XXN .mds	_ " _			
wz XXN .mds	Tool offset data			
wwz XXN .mds	Tool setting data			
zwz XXN .mds	Current tool data			
np XXN .mds	Zero shift data			
pnc N .red	Settings for the OP (description see Appendix 5)			
modul N .dsc	Settings for the OP (including machine name)			
p01.sps	PLC program			
auto N .din	Autostart DIN file			
refer N .din	Homing cycle program			

The characters **XX** stand in this case for the (variable) NC address (01...49) and the **N** for the channel number (1 or 2).

All DIN programs of the selected part project are also included.

3.3 Backup medium

Part projects and NC configuration data are filed on the backup medium.

Part projects are taken over as complete directories from the user path.

4 RED files

Set configuration data are stored in textual form in the RED files. There exists one such file for the NC interface in the OP (pnc.red) as well as in each case one for each NC (one each for each channel) in the NC file management (pnc1.red or pnc2.red).

Each RED file consists of a set of entries in the form:

Designator = Contents

Each entry must be in a separate line. Any number of blank characters can stand before and after the equal sign. A double hyphen at the line start identifies a comment and can thus be used for deactivating an entry.

A standard value which is used if no entry is provided exists for (almost) every designator.

Apart from the entries described below, further entries, which are required for test and diagnosis purposes, can stand in the files.

Designator	default	Contents / Use		
Data paths (absolu	tely nec	essary entries)		
USERPFAD		Path to the storage medium in which the user data are stored (part projects).		
BACKUPPFAD		Identification of the drive and path for all backup actions.		
INTERNPFAD		Path on the storage medium for read only internal data (language files, help files) and default path for the conditionally necessary data paths.		
Conditionally nece	ssary da	ta paths		
TEMPPFAD	Internal path	Path on the storage medium in which all internal data of the operator interface should be stored, such as temporary files and session files.		
AMKGLOBAL	Internal path	Path on the storage medium from which all global data of the operator interface should be read, such as error texts, AMK logo and font file.		
Parameterization o	f the BD	E		
UserKeys		max. 8 Ascii characters for allocating the <uk1><uk8></uk8></uk1>		

4.1 RED file in the Operator Panel

Designator	default	Contents / Use			
Sbus-Kanal	com2+	Initialization string for the SBUS in the form:			
		port [± [adr]] {, port [± [adr]] }			
		port_com1 - ser. interface1 of the PC			
		com2 - ser. interface2 of the PC			
		abksyn - fibre optic cable to ABK02			
		abkasyn - V422 on ABK02			
		+ Port undertakes master function			
		- Port is slave			
		adr phys. Sbus address of the port			
LwILicht	1	Luminance of the fibre optic transmitter on the ABK02			
Sbus-Timeout	5.5	Timeout time (in s) for file and command accesses through the SBUS			
StartPause	0	Delay of the start of the operator interface (in 50 ms).			
KeyDelay	15	Delay (in 50 ms) of the keyboard query for the softkey and manual movement keys.			
Titel	1	Display and operation of the title picture:			
		0 - Title picture is not displayed			
		1 - Title picture is displayed during the start process			
		2 - Title picture must be confirmed by key			
		3 - Title picture must be confirmed by 📈+ Enter			
StartOnLine	1	With <>0 the on-line module is started after start, with 0 the off-line module.			
TRANS-SS	0	Number of the serial interface (Com) for serial transfer			
TRANS-BOT	2	Start character for serial transfer			
TRANS-EOT	3	End character for serial transfer			

Peripheral functions

-			
PeripherieDelay	1	Time interval (in 50 ms) of the peripheral query.	
P		Definition of peripheral functions (see Commissioning item)	
AX-SCHALTER		Designations of the positions of the axis selector switch	

Adaptation of NC operating functions

VB-JOG-NORM	500	Speed during the simple JOG movement	
VB-JOG-FAST	5000	Speed during the fast JOG movement	
MDI-AUTO-LF	0	The automatic LF function is switched on in the Mdi with <>0	

Designator	default	Contents / Use		
ANZEIGEN	1,0,	List of the activated and deactivated display types		
ANZEIGE	0	Active display		
ANZEIGERATE	0.2	Repetition rate (in s) of the display freshening		
POS-RUNDEN	1	Positions are rounded in the display with <>0		
TEST-REFER	0	A test is made before each start command (automatic or manual) whether the machine has executed the homing cycle completely with <>0		
Linking				
VERKETTUNG	0	Parameterizable linking is used as linking program with 1, otherwise programmable.		
VKT-NAME		Name of the active linking program		
VKM-PFAD		Path to the program pool for the parameterizable linking		
VKM-ANLAGE		Name (and subpath) for the parameterizable linking		
VKM-PLAETZE		Number of machine locations		
VKM-ZEILE0		Is created for each reserved workplace of the parameterizable		
VKM-ZEILE1		linking with the syntax:		
		Name[,Offset±Register]		
VKM-TEILE	0,0,	State of the submasks in the parameterizable linking		
		• • •		
Entries which are u	ised only	y for test purposes		
Starttrace	0	The inner functions of the program booting are displayed on the screen with <>0		
Debug	0	Activating different debug functions		
TokenTimeout	?	Setting the token timeout time		
Pdu-Trace	0	All PDUs processed by the Sbus distributor are listed in the file "sbtrace.txt" with <>0.		
NCSimulation	0	The NC is simulated with <>0.		

4.2 RED file in the NC

Designator	default	Contents / Use		
NC-Typ	0	0=general; 1=part memory		
Referenzart	0	Type of the common homing cycle 0=sequence, 1=program		
Referenzfahrt	0,0,	List of the homing cycle priorities of the axes		
Handradtyp	0	Set handwheel		
SyncZJog	1	Factor for assessing the handwheel resolution		
HandradLokal	0,0,	List of the axes with local handwheels		
Fast-Nc-Prog-Start	0	The NC program start is executed without setting function with <>0.		
ProjektName		Active part project		
DinName		Active DIN program		

5 Layout of text files for error messages

There are two types of text files with defined layout for each error source (control module):

- Abbreviations
- Description texts (in different languages)

The files must be present in pure text format (PC8-Ascii) and must not contain any formatting commands (also no tabulators). The line end is identified by the CR-NL sequence.

Abbreviations

These files serve for decoding the error numbers and error identifications in short term. They are broken down into sections for this purpose. Each section is introduced by an empty square bracket and serves for decoding one or several error numbers (function numbers). Each error number must stand in a separate line, consisting of error number and short text. Detailing of the error numbers in the form of the assignment of terms to error identifications can then be provided.

Comments are identified by two hyphens.

Example:

[] 2010 ERROR_SBMAN_VERT 2011 ERROR_SBMAN_BUS 2019 ERROR_WSP [*2019] 1 ERR_WSP_SP_FILE 2 ERR_WSP_GRF_UNDEF 3 ERR_WSP_ZIEL_START 4 ERR_WSP_NC_NBEREIT 5 ERR_WSP_FLSNCFKT 6 ERR_WSP_TIMEOUT	****	Section start Error number 2010 Error number 2011 Error number 2019 Start of detailing for error No. 2019 Error identification 1 for error No. 2019
	r ₽	Start of next section

Machine-related error numbers are possible for the PSU errors.

Example: [*113*milling] ⇒	Error number 113 of the "milling" machine
---------------------------	---

Description texts

The description texts contain detailed explanations for the abbreviations. They exist for each source module in different languages. Each explanation starts with a list of the abbreviations for which the following text applies, whereby an exclamation mark must stand directly before each designation and this always at the line start. The description text can extend over several lines, but must not contain any exclamation marks at the line start. The exclamation mark of the next short term serves as text end identifier.

Example:

!ERR_LADER_SERVER_NR_LESEN_RETURN !ERR_BEDIENFELD_NICHT_AKTIV_ERROR !ERR_NC_STATUS !ERR_DIAGNOSE_DATEN !ERR_DIAGNOSE_ERROR_KLASSE

The command which was sent to the NC through the SBUS received a negative acknowledgement from there.

It should be checked why the command could not be correctly accepted or executed!

!ERROR_SBMAN_VERT

The file names are defined as follows:

Abbreviations	QQQ.err
Description texts	QQQ_LLL.erh

The QQQ stands for the possible error sources:

AZ computer:	AZR
NC kernel:	MC
PLC kernel:	PS
Operating program:	PNC
PLC-AWL:	PSU

LLL stands for the language used:

German	ger
English	eng

The files for the PLC-AWL error messages do not exist yet but can be produced by the AWL programmer if needed.

6 Simulation of the NC in the OP

To activate simple NC simulation in the OP, the entry

NCSimulation = 1

must be present in the RED file. The simulation requires a file management which is created as path in the OP. This is searched for as standard under 'c:\nc_prog\dv_ncsim\'. Should another be used, this must be defined as entry in the RED file

NCSimulationPath =

The path for the files of the simulation must exist before the program is selected. So that the simulation can work, the configuration files of the NC and of the OP must be present in this directory (can also be loaded with the OP program item 'Commissioning - Load nc setup).

Caution: Simulation can be switched on only in some software versions!

7 DNC-Data Format

7.1 Message Structure

Each message consists of a Header section and a Data section. These are framed by a single byte start and end character:

	BOT	Header	Data	EOT
--	-----	--------	------	-----

Each Header and Data sections can contain a number of entries. Each entry is on a separate line, terminated by a [CR]. The order of the entries is not important. Elements that are not required are not transmitted, so only some of the possible entries are transmitted.

Many entries consist of a Designator followed by text or a number, in which case they must be separated by a [SPACE].

Start- and End Characters

These characters are configurable, or can be switched off completely. Default values are:

- BOT: 02 [^B]
- EOT: 03 [^C]

Header

The Header consists of a Header block which can be framed by a start message and end message:

BOK Header block EOK

The start message (BOK) and end messages (EOK) are configurable, or can be switched off completely.

The following 3 Header block entries are possible:

Designater	Parameter	Description	Example
MASCHINE	Text	Name of the maschine	MASCHINE Lathe
PROJEKT	Text	Name of the project	PROJEKT Part
TYP	Р	DIN-program with number	TYP P
	W	Tool correction data	TYP W
	Ν	Zero point offset data	TYP N

If no Project name is specified, the data is associated to the active (selected) project.

At present the MACHINE Designator is not implemented and can be omitted.

Data

The Data section consists of a number of data block each with a number of entries. Each data block can begin with a start message. The entire Data section can be termibated by an End message:

BOD	Data block	BOD	Data block	 EOD

The start message (BOD) and (EOD) are configurable, or can be switched off completely.

DIN Program

The data block begins with the program number:

Designator	Parameter	Description	Example
NR	number	Number of the program	NR 100

This is followed by the complete DIN program. The number of program lines is unlimited.

Tool correction data

Tool Correction Data are a sequence of single tools. The data blocks start with the tool number:

Designator	Parameter	Description	Example
NR	number	Marks the beginning of a new data block and contains the tool number	NR 16

This is followed by the following, in any order:

Designator	Parameter	Description	Examole
LN	Maß	Tool length	LN 12.4
RA	Maß	Tool radius	RA 0.7
A?	Maß	Tool offset of assigned axis	AZ 20.5
ТА	Maß	Updated tool life	
ТМ	Maß	Tool life remainder	
TS	Maß	Alternative tool number	
TN	Maß	T-number	

Zero-point-offset data

Zero Point Offset Data are a sequence of single blocks. The data blocks start with the block number:

Designator	Parameter	Description	Example
NR	number	Marks the beginning of a new data block	NR 3
		and contains the corresponding number	

This is followed by the following, in any order:

Designator	Parameter	Description	Example
A?	dimension	Offset along the specified axis	AZ 20.5

7.2 Examples

Example for DIN-program:

PROJECT LATHE TYP P NR 100 %100 G01 X100 Z100 F10000 G01 X0 G04 X10 M30

Example Tool correction data (Standard):

PROJECT LATHE TYP W NR 1 RA 0.9 AX 100 NR 2 RA 0.5 NR 5 RA 0.5 AX 80 AZ 2

Example Tool correction data (with start- and endtext):

TXA PROJECT LATHE TYP W	-> starttext for head
TXE	-> endtext for head
DATA	-> starttext for data
NR 1	
RA 0.9	
AX 100	
DATA	-> starttext for data
NR 2	
RA 0.5	
DATA	-> starttext f ür data
NR 5	
RA 0.5	
AX 80	
AZ 20	
DATE	-> endtext for data

8 I / O Definition

12 Input and 4 Output ports are supported and addressable by the user. The physical addresses of the ports must be in the RED file. The port addresses can be seen in the menu item "Commisioning - Diagnosis - Perpherals" under the port addresses.

Direct Input and Output

If the port addresses are not set in the RED file, default direct inputs are defined 300H...303H and 310H...317H and direct outputs are defined as 300H...303H. The port addresses can be seen in menue item "Startup-Diagnosis-Peripherals". To change these preset addresses, the keywords IN or OUT must be used in the RED file. For example the entry:

OUT=0x220,0x221

defines the four output ports as: 220H, 221H, 302H and 303H

Ein- und Ausgabe über CANopen-Module

To use the module for I/O, the CAN ID list of the module must be defined in the RED file. For example:

CAN-ID=1,5,7

The inputs and output ports are then assigned to the module in numerical order. Individual ports can be masked out by the IN or OUT keywords in the RED file. For example:

OUT=CAN0,CAN2, CAN3,CAN4

Mixed Input and Output

The IN and OUT keywords can also be used to mix dirct I/O with CANopen ports in the RED file as described above. It is important to use the CAN-ID keyword to differentiate them.

An offset value must be defined as follows:

Definition of an offset mask:

Designator = Type : Number , Element

- Designator: Any term of maximum 18 characters; this term is displayed after calling the online correction
- Type: wz for tool correction data np - for number zero point offset data
- Number: Data block number (1...40 for TC), (1...7 for ZPO)
- Element: Name of the the data block element
 - Axis name
 - L for tool length offset
 - R for tool radius offset

Example: Length = wz : 1, X

Blanks are permissible within the line. With 2 hyphens (--) at the beginning the line has no effect.

9 Impressum

Title	NC-Commissioning
Objective	Commissioning of the operation panel
Part-Number	27878
History	Date 1998/08
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Publisher	AMK Arnold Müller Antriebs- und Steuerungstechnik GmbH & Co. KG Gaußstraße 37 – 39, 73230 Kirchheim/Teck Tel.: 07021/5005-0, Fax: 07021/5005-176 E-Mail: <u>info@amk-antriebe.de</u>

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